Remplacer delay()

main.c

```c
    uint32_t last_led_ts = 0;
    uint32_t last_pot_servo_ts = 0;
    uint32_t 

    while (1) {
        uint32_t now = get_ms();

        if (now - last_led_ts >= 500) {
            last_led_ts = now;
            led_toggle();
        }

        if (now - last_pot_servo_ts >= 10) {
            last_pot_servo_ts = now;
            uint32_t angle = pot_read() * 180 / 4095;
            servo_set(angle);
        }


    }
}
```

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