

Arduino

- [Remplacer delay\(\)](#)

Remplacer delay()

C main.c

```
7     uint32_t last_led_ts = 0;
8     uint32_t last_pot_servo_ts = 0;
9     uint32_t
10
11     while (1) {
12         uint32_t now = get_ms();
13
14         if (now - last_led_ts >= 500) {
15             last_led_ts = now;
16             led_toggle();
17         }
18
19         if (now - last_pot_servo_ts >= 10) {
20             last_pot_servo_ts = now;
21             uint32_t angle = pot_read() * 180 / 4095;
22             servo_set(angle);
23         }
24
25     }
26 }
27 }
```